

# Probabilistic Event Calculus based on Markov Logic Networks

Anastasios Skarlatidis<sup>1,2</sup>, Georgios Paliouras<sup>1</sup>,  
George Vouros<sup>2</sup> and Alexander Artikis<sup>1</sup>

<sup>1</sup> Institute of Informatics and Telecommunications  
NCSR "Demokritos", Athens 15310, Greece  
{anskarl,paliourg,a.artikis}@iit.demokritos.gr

<sup>2</sup> Department of Information and Communication Systems Engineering,  
University of the Aegean, Samos, Greece  
georgev@aegean.gr

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# Outline

Introduction

Event Calculus in Markov Logic Networks

Representing Event Calculus Axioms in MLN

Behaviour of Event Calculus in MLN

Experiments: Activity Recognition

# Event Recognition

- ▶ Variety of application domains, e.g. health care monitoring, public transport management, activity recognition etc
- ▶ Input:
  - ▶ *Low-level events* (LLE) — time-stamped symbols
  - ▶ LLE come from different sources/sensors
  - ▶ e.g. happens(walking(id1), 10), happens(active(id2), 10), ...
- ▶ Output:
  - ▶ Recognised *high-level events* (HLE)
  - ▶ e.g. holdsAt(meeting(id1,id2), 11), holdsAt(meeting(id1,id2), 12), ...
- ▶ HLE: Relational structure over other sub-events (HLE or LLE)

## Methods:

- ▶ Logic-based — very expressive
- ▶ Probabilistic-based — handle uncertainty

# Event Recognition

## **Requirements:**

- ▶ Formal representation language
- ▶ Handle uncertainty

## **The method combines:**

- ▶ Event Calculus — representation
- ▶ Markov Logic Networks — probabilistic inference

## Markov Logic Networks (MLN) — in a nutshell

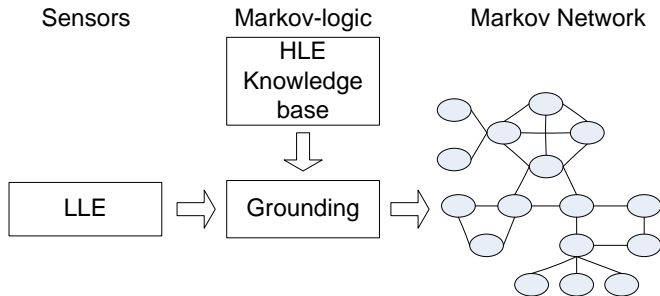
- ▶ First-order logic  $\rightarrow$  set of hard constraints
- ▶ Syntactically: weighted first-order logic formulas  $(F_i, w_i)$
- ▶ Semantically:  $(F_i, w_i)$  represents a probability distribution over possible worlds (or Herbrand interpretations)

$$P(X = x) = \frac{1}{Z} \exp \left( \sum_i w_i n_i(x) \right)$$

- ▶ possible world
- ▶ partition function
- ▶ number of satisfied ground formulas

A world violating formulas becomes less probable, but not impossible!

# Markov Logic Networks (MLN) — in a nutshell



- ▶ Formula  $\rightarrow$  clausal form
- ▶ Clauses are grounded according to the domain of their distinct variables
- ▶ Existentially quantified variables are replaced by the disjunction of their groundings:  $\forall X \exists Y p(Y) \wedge q(X) \equiv (p(1) \wedge q(X)) \vee (p(2) \wedge q(X)) \vee \dots$
- ▶ Open-world assumption for non-evidence predicates

# Event Calculus

- ▶ Reasoning about events and their effects
- ▶ A variety of different dialects
- ▶ Ontology
  - ▶ Timepoints
  - ▶ Events → low-level events
  - ▶ Fluents → high-level events
- ▶ Core domain-independent axioms
  - ▶ Define whether a fluent holds or not at a specific timepoint
  - ▶ **Inertia**: fluents persist over time, unless affected by some event
- ▶ Domain-dependent definitions → HLE definitions
  - ▶ Initiation of a fluent
  - ▶ Termination of a fluent

## Representing Event Calculus in MLN

Some axioms from Shanahan's Full Event Calculus:

$$\left. \begin{aligned} \text{holdsAt}(F, T) \leftarrow & \text{happens}(E, T_0) \wedge \\ & \text{initiates}(E, F, T_0) \wedge \\ & T_0 < T \wedge \\ & \neg \text{clipped}(F, T_0, T) \end{aligned} \right\} F \times E \times T \times T_0$$

$$\left. \begin{aligned} \text{clipped}(F, T_0, T_1) \leftrightarrow & \exists E, T \\ & \text{happens}(E, T) \wedge \\ & T_0 \leq T < T_1 \wedge \\ & \text{terminates}(E, F, T) \end{aligned} \right\} F \times E \times T \times T_0 \times T_1$$



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- ▶ Huge number of groundings

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- ▶ Huge number of groundings
- ▶ Combinatorial explosion

# Discrete Event Calculus

- ▶ Logically equivalent with EC, when the domain of timepoints is limited to integers
- ▶ Axioms are defined over successive timepoints

$$\left. \begin{array}{l} \textit{holdsAt}(F, T + 1) \leftarrow \\ \quad \textit{happens}(E, T) \wedge \\ \quad \textit{initiates}(E, F, T) \end{array} \right\} F \times E \times T$$
$$\left. \begin{array}{l} \textit{holdsAt}(F, T + 1) \leftarrow \\ \quad \textit{holdsAt}(F, T) \wedge \\ \quad \neg \exists E \textit{ happens}(E, T) \wedge \\ \quad \textit{terminates}(E, F, T) \end{array} \right\} F \times E \times T$$

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Creates  $2^{|E|}$  clauses

# Simplifying Discrete Event Calculus

General form of domain-dependent HLE definition:

$$\begin{aligned} \textit{initiatedAt}(\textit{fluent}_k, T) \leftarrow \\ \textit{happens}(\textit{event}_n, T) \wedge \dots \wedge \\ \textit{Conditions}[T] \end{aligned}$$

$$\begin{aligned} \textit{terminatedAt}(\textit{fluent}_k, T) \leftarrow \\ \textit{happens}(\textit{event}_n, T) \wedge \dots \wedge \\ \textit{Conditions}[T] \end{aligned}$$

# Simplifying Discrete Event Calculus

$holdsAt(F, T + 1) \leftarrow$

$happens(E, T) \wedge$   
 $initiates(E, F, T)$

$holdsAt(F, T + 1) \leftarrow$

$initiatedAt(F, T)$



# Simplifying Discrete Event Calculus

$$\begin{aligned} \text{holdsAt}(F, T + 1) \leftarrow \\ \text{happens}(E, T) \wedge \\ \text{initiates}(E, F, T) \end{aligned}$$
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$$\begin{aligned} \text{holdsAt}(F, T + 1) \leftarrow \\ \text{holdsAt}(F, T) \wedge \\ \neg \text{terminatedAt}(F, T) \end{aligned}$$




# Simplified Discrete Event Calculus

## When a fluent holds:

$$\left. \begin{array}{l} \text{holdsAt}(F, T + 1) \leftarrow \\ \text{initiatedAt}(F, T) \end{array} \right\} F \times T$$

$$\left. \begin{array}{l} \text{holdsAt}(F, T + 1) \leftarrow \\ \text{holdsAt}(F, T) \wedge \\ \neg \text{terminatedAt}(F, T) \end{array} \right\} F \times T$$

## When a fluent does not hold:

$$\left. \begin{array}{l} \neg \text{holdsAt}(F, T + 1) \leftarrow \\ \text{terminatedAt}(F, T) \end{array} \right\} F \times T$$

$$\left. \begin{array}{l} \neg \text{holdsAt}(F, T + 1) \leftarrow \\ \neg \text{holdsAt}(F, T) \wedge \\ \neg \text{initiatedAt}(F, T) \end{array} \right\} F \times T$$

## Example: HLE definition

When the fluent 'meeting' is initiated:

$$\begin{aligned} \mathbf{initiatedAt}(\mathbf{meeting}, \mathbf{T}) \leftarrow & \\ & \mathit{happens}(\mathit{event}_1, T) \wedge \\ & \neg \mathit{happens}(\mathit{event}_2, T) \wedge \\ & \mathit{distance}(\mathit{close}, T) \end{aligned}$$

$$\begin{aligned} \mathbf{initiatedAt}(\mathbf{meeting}, \mathbf{T}) \leftarrow & \\ & \mathit{happens}(\mathit{event}_3, T) \wedge \\ & \neg \mathit{happens}(\mathit{event}_1, T) \wedge \\ & \neg \mathit{happens}(\mathit{event}_2, T) \wedge \\ & \mathit{distance}(\mathit{close}, T) \end{aligned}$$

When the fluent 'meeting' is terminated:

$$\begin{aligned} \mathbf{terminatedAt}(\mathbf{meeting}, \mathbf{T}) \leftarrow & \\ & \mathit{happens}(\mathit{event}_4, T) \end{aligned}$$

...

# Open-world semantics in MLN

Domain-dependent definitions:

- ▶ Conditions under which HLE are initiated or terminated
- ▶ Open-world assumption for non-evidence predicates:  
initiatedAt, terminatedAt and holdsAt

When something is happening that it is not defined in the domain-dependent definitions:

- ▶ Cannot determine whether a fluent holds or not
- ▶ **Loss of the inertia**
- ▶ This is also known as the *frame problem*
- ▶ Solution: predicate completion

## Predicate completion

HLE definitions = {

- initiatedAt(meeting, T) ←**  
*happens(event<sub>1</sub>, T) ∧*  
*¬happens(event<sub>2</sub>, T) ∧*  
*distance(close, T)*
- initiatedAt(meeting, T) ←**  
*happens(event<sub>3</sub>, T) ∧*  
*¬happens(event<sub>1</sub>, T) ∧*  
*¬happens(event<sub>2</sub>, T) ∧*  
*distance(close, T)*
- ...

# Predicate completion

HLE definitions =

**initiatedAt(meeting, T)**  $\leftarrow$   
*happens(event<sub>1</sub>, T)  $\wedge$*   
 *$\neg$ happens(event<sub>2</sub>, T)  $\wedge$*   
*distance(close, T)*

**initiatedAt(meeting, T)**  $\leftarrow$   
*happens(event<sub>3</sub>, T)  $\wedge$*   
 *$\neg$ happens(event<sub>1</sub>, T)  $\wedge$*   
 *$\neg$ happens(event<sub>2</sub>, T)  $\wedge$*   
*distance(close, T)*

...

Completion constraints =  
(automatically generated)

**initiatedAt(meeting, T)**  $\rightarrow$   
*[happens(event<sub>1</sub>, T)  $\wedge$*   
 *$\neg$ happens(event<sub>2</sub>, T)  $\wedge$*   
*distance(close, T)]  $\vee$*   
*[happens(event<sub>3</sub>, T)  $\wedge$*   
 *$\neg$ happens(event<sub>1</sub>, T)  $\wedge$*   
 *$\neg$ happens(event<sub>2</sub>, T)  $\wedge$*   
*distance(close, T)]*

...

# Predicate completion

HLE definitions = {

- 1.5**  $\text{initiatedAt}(\text{meeting}, T) \leftarrow$   
 $\text{happens}(\text{event}_1, T) \wedge$   
 $\neg \text{happens}(\text{event}_2, T) \wedge$   
 $\text{distance}(\text{close}, T)$
- 0.25**  $\text{initiatedAt}(\text{meeting}, T) \leftarrow$   
 $\text{happens}(\text{event}_3, T) \wedge$   
 $\neg \text{happens}(\text{event}_1, T) \wedge$   
 $\neg \text{happens}(\text{event}_2, T) \wedge$   
 $\text{distance}(\text{close}, T)$
- ...

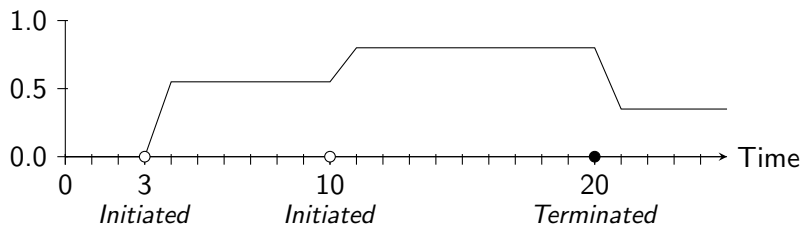
Completion constraints =  
(automatically generated) {

- 4.0**  $\text{initiatedAt}(\text{meeting}, T) \rightarrow$   
 $[\text{happens}(\text{event}_1, T) \wedge$   
 $\neg \text{happens}(\text{event}_2, T) \wedge$   
 $\text{distance}(\text{close}, T)] \vee$   
 $[\text{happens}(\text{event}_3, T) \wedge$   
 $\neg \text{happens}(\text{event}_1, T) \wedge$   
 $\neg \text{happens}(\text{event}_2, T) \wedge$   
 $\text{distance}(\text{close}, T)]$
- ...

## Inertia in MLN

EC domain-independent axioms are hard-constrained and:

1. Only HLE definitions are soft-constrained

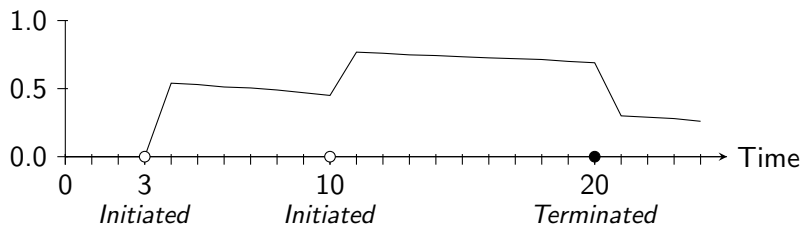


$$P(\text{world}) \propto \exp\left(\sum(\text{weights of formulas it satisfies})\right)$$

## Inertia in MLN

EC domain-independent axioms are hard-constrained and:

2. Only HLE definitions are soft-constrained and the termination rules in the completion constraints



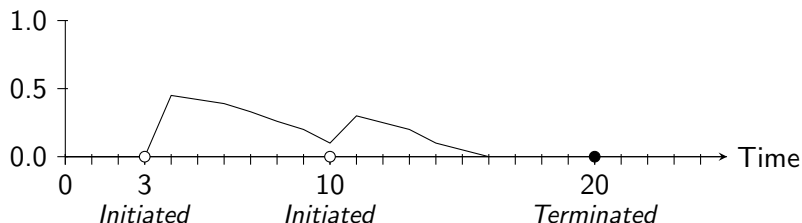
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EC domain-independent axioms are hard-constrained and:

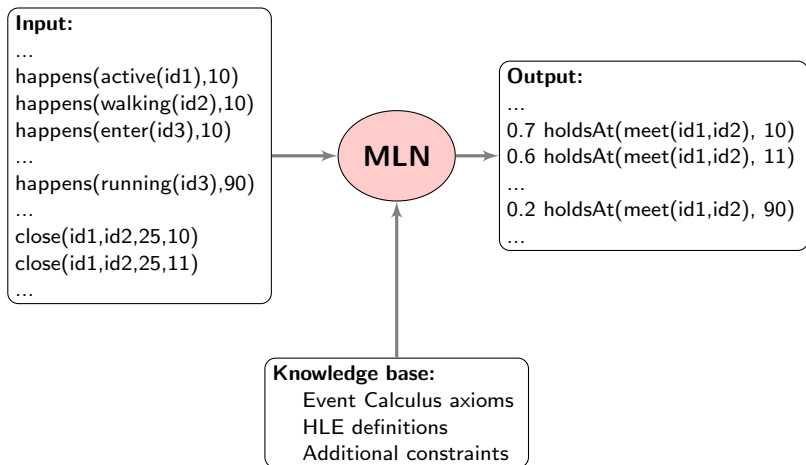
2. Only HLE definitions are soft-constrained and the termination rules in the completion constraints



$$P(\text{world}) \propto \exp\left(\sum(\text{weights of formulas it satisfies})\right)$$

## Experiments — CAVIAR dataset

- ▶ 28 surveillance videos
- ▶ LLE: active, inactive, walking, running, enter and exit
- ▶ HLE: *meeting, moving, fighting and leaving an object*



## Experiments — results

### ▶ EC-LP:

- ▶ Logic-programming based EC
- ▶ Knowledge base of HLE for CAVIAR dataset

### ▶ DEC-MLN:

- ▶ Markov Logic Networks based EC
- ▶ Manually adjusted weight values for the HLE *meeting*:
  - ▶ weak values — low confidence
  - ▶ strong values — high confidence
- ▶ DEC-MLN<sub>a</sub>: soft-constrained HLE definitions
- ▶ DEC-MLN<sub>b</sub>: soft-constrained HLE definitions and termination rules in the completion constraints

Method	TP	FP	FN	Precision	Recall
EC-LP	3099	2258	525	0.578	<b>0.855</b>
DEC-MLN <sub>a</sub>	3048	1762	576	0.633	0.841
DEC-MLN <sub>b</sub>	3048	1154	576	<b>0.725</b>	0.841

Source KB and dataset files can be found in <http://www.iit.demokritos.gr/~anskarl>

# Conclusions

- ▶ Probabilistic extension of Event Calculus
- ▶ Formal and declarative semantics
- ▶ Probabilistic inference
- ▶ Emphasis on simplifying the axioms of the EC — reduce the size and the complexity of the network
- ▶ Deterministic or probabilistic control of the inertia

## **Future directions:**

- ▶ Machine learning — estimate weight values
- ▶ Experiments in other real-world data sets

Thank you for your attention!

Any questions?